

# Sparsity in Linear Predictive Coding of Speech

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# Motivation

In one sentence

- ▶ Revisiting early concepts in speech and audio analysis in light of the new development in sparse representation.

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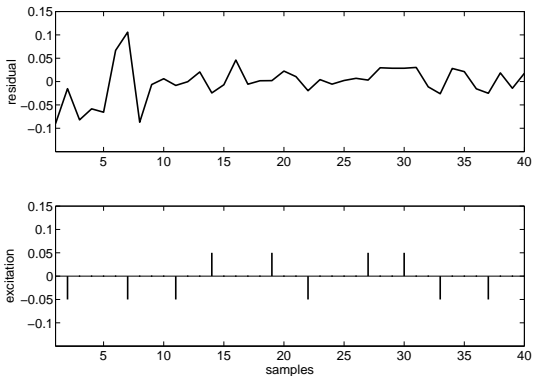
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# Motivation

## Why sparsity in Linear Prediction?

- ▶ Initial idea: reduce the mismatch between a “white noise”-like prediction residual and a *sparse* approximation.



# Motivation

## Why sparsity in Linear Predictive Analysis-by-Synthesis coding?

- ▶ One of the earliest problems in speech coding!

$$\hat{\mathbf{r}} = \arg \min_{\mathbf{r}} \|\mathbf{W}(\mathbf{x} - \mathbf{H}\mathbf{r})\|_2 + \gamma \|\mathbf{a}\|_0$$

- ▶ Solution is impractical due to the combinatorial nature of the problem.
- ▶ Suboptimal algorithm was proposed to find one pulse at the time: Multi-Pulse Encoding (MPE) (= Matching Pursuit).

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# Sparse Linear Prediction

## Fundamentals 1/2

- ▶ A speech sample  $x(n)$  is approximated as a linear combination of past samples:

$$x(n) = \sum_{k=1}^K a_k x(n-k) + e(n),$$

where  $\{a_k\}$  are the prediction coefficients,  $e(n)$  is prediction error. In matrix form becomes:

$$\mathbf{x} = \mathbf{X}\mathbf{a} + \mathbf{e}.$$

- ▶ We can consider a generalized optimization framework to find  $\mathbf{a}$ :

$$\min_{\mathbf{a}} \|\mathbf{x} - \mathbf{X}\mathbf{a}\|_p^p + \gamma \|\mathbf{a}\|_k^k.$$

- ▶ How to choose  $p$ ,  $k$  and  $\gamma$  depends on the kind of applications we want to implement.

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- ▶ If we want to introduce sparsity in the LP optimization framework, we can set  $p = 0$  and  $k = 0$ :

$$\min_{\mathbf{a}} \|\mathbf{x} - \mathbf{X}\mathbf{a}\|_0 + \gamma \|\mathbf{a}\|_0,$$

- ▶  $\gamma$  relates to *how sparse*  $\mathbf{a}$  is (prior knowledge of  $\mathbf{a}$ ).
- ▶ 1-norm used as a convex relaxation of the 0-norm:

$$\min_{\mathbf{a}} \|\mathbf{x} - \mathbf{X}\mathbf{a}\|_1 + \gamma \|\mathbf{a}\|_1.$$



# Sparse Linear Prediction

## Finding a Sparse Residual

- ▶ Consider now the case of a short-term predictor that engenders a sparse residual ( $\gamma = 0$ ):

$$\min_{\mathbf{a}} \|\mathbf{x} - \mathbf{X}\mathbf{a}\|_1.$$

- ▶ ML approach when the error sequence is considered to be a set of i.i.d. Laplacian random variables.
- ▶ Sparser residual beneficial for both analysis and coding purposes.

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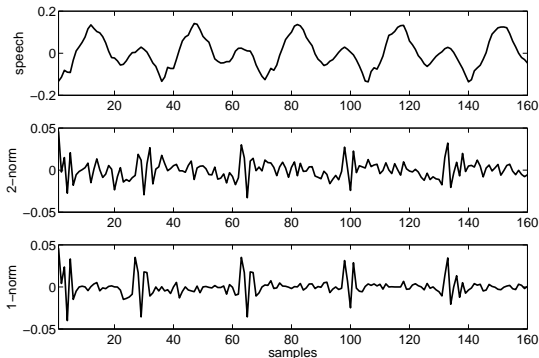
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# Sparse Linear Prediction

## Finding a Sparse Residual - Example



The spiky train characteristic of voiced speech is retrieved more accurately when we look for a sparse residual.

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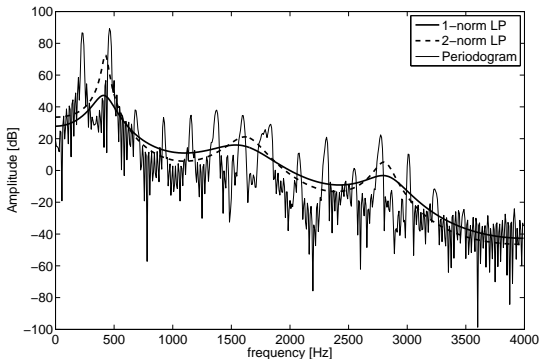
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# Sparse Linear Prediction

## Finding a Sparse Residual - Example



The lower emphasis on peaks in the envelope, when 1-norm minimization is employed, is a direct consequence of the ability to retrieve the spiky pitch excitation.

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# Sparse Linear Prediction

## Finding a High-Order Sparse Predictor

- ▶ Consider the cascade of a short-term linear predictor  $F(z)$  and a long-term linear predictor  $P(z)$  to remove respectively near-sample redundancies:

$$A(z) = \left( 1 - \sum_{k=1}^{N_f} f_k z^{-k} \right) \left( 1 - \sum_{k=1}^{N_p} g_k z^{-(T_p+k-1)} \right).$$

- ▶ The resulting prediction coefficient vector  $\mathbf{a} = \{a_k\}$  of the high order polynomial  $A(z)$  will therefore be highly sparse.
- ▶ We can impose sparsity on a high-order predictor:

$$\min_{\mathbf{a}} \|\mathbf{x} - \mathbf{X}\mathbf{a}\|_p^p + \gamma \|\mathbf{a}\|_1.$$

- ▶ When  $p = 2$  minimum variance approach,  $p = 1$  encourages sparsity also on the residual.

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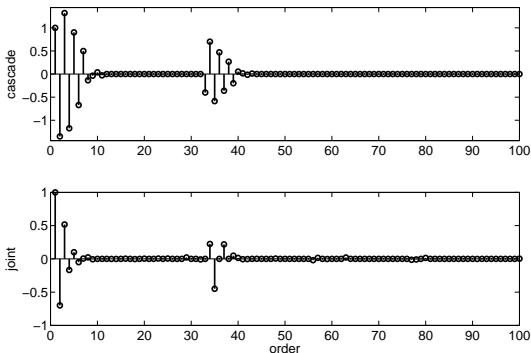
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# Sparse Linear Prediction

## Finding a High-Order Sparse Predictor - Example



The prediction coefficients vector is similar to the multiplication of the short-term prediction filter and long-term prediction filter usually obtained in cascade.

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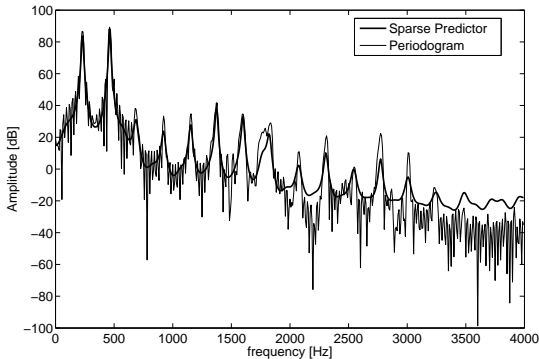
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# Sparse Linear Prediction

## Finding a High-Order Sparse Predictor - Example



Spectral modeling properties of a high order sparse predictor with only nine nonzero coefficients.

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# Sparse Linear Prediction

## Finding a High-Order Sparse Predictor

- ▶ The purpose of the high order sparse predictor is to model the *whole* spectrum, i.e., the spectral envelope and the spectral harmonics.
- ▶  $\gamma$  controls the sparsity of the prediction coefficient vector. If  $\gamma$  is chosen appropriately, we can obtain again  $F(z)$  and  $P(z)$  through approximate factorization.
- ▶ Intrinsic model order selection!

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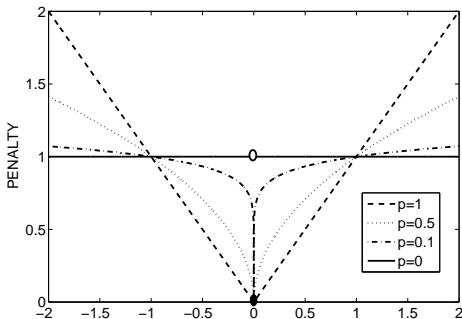
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# Sparse Linear Prediction

## Reducing the 1-norm 0-norm mismatch



- ▶ Reweighted 1-norm minimization balances the dependence on the magnitude of the 1-norm.
- ▶ Changing the cost function and moving the problem towards the 0-norm minimization with convex tools (convergence to the log-sum penalty function).

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# Sparse Linear Prediction

## Compressed Sensing in Sparse LP

- ▶ If sparse, our solution lies in a subspace of reduced dimensionality where the Euclidean distance between all points in the signal model is preserved.
- ▶ Two ingredients needed for CS: a domain where the signal is sparse and the sparsity level  $T$ .
- ▶ Exploiting knowledge of  $T$  a limited number of  $M \propto T$  random projections are sufficient to recover our predictors and sparse residual with high accuracy.
- ▶ The *shrinkage* of the minimization problem in a lower dimensional space will have a clear impact on the complexity.

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## Compressed Sensing in Sparse LP

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- ▶ Original MPE problem (known predictor):

$$\hat{\mathbf{r}} = \arg \min_{\mathbf{r}} \|\mathbf{x} - \mathbf{H}\mathbf{r}\|_2^2 \quad \text{s.t.} \quad \|\mathbf{r}\|_0 = K.$$

- ▶ CS Formulation:

$$\hat{\mathbf{r}} = \arg \min_{\mathbf{r}} \|\mathbf{r}\|_1 + \gamma \|\Phi\mathbf{x} - \Phi\mathbf{H}\mathbf{r}\|_2^2.$$

- ▶ 1-norm global optimization as convex relaxation of the 0-norm: near-optimal selection of sparse excitation.
- ▶ Sparsity-knowledge-based *shrinkage*: reduction of constraints  $\rightarrow$  computationally faster.

# Sparse Linear Prediction

## Compressed Sensing in Sparse LP

- ▶ To adapt CS principles to the estimation of the predictor as well, consider the relation between the synthesis matrix  $\mathbf{H}$  and the analysis matrix  $\mathbf{A}$  ( $\mathbf{A} = \mathbf{H}^+$ ):

$$\min_{\mathbf{a}, \mathbf{r}} \|\mathbf{r}\|_1 \quad \text{s.t.} \quad \Phi \mathbf{r} = \Phi(\mathbf{x} - \mathbf{X}\mathbf{a}).$$

- ▶ Equivalent to our original formulation projected onto a lower-dimensional space.
- ▶ When looking for a high order sparse predictor, similarly:

$$\min_{\mathbf{a}, \mathbf{r}} \|\mathbf{r}\|_1 + \gamma \|\mathbf{a}\|_1 \quad \text{s.t.} \quad \Phi \mathbf{r} = \Phi(\mathbf{x} - \mathbf{X}\mathbf{a}).$$

- ▶ Both formulation can also involve a reweighting procedure.

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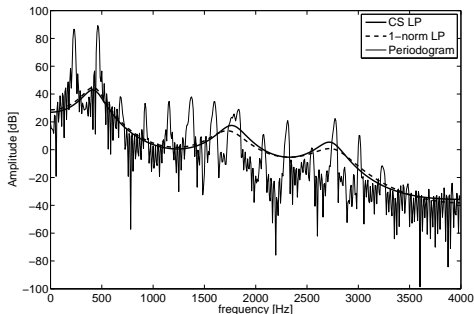
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## Compressed Sensing in Sparse LP - Example



1-norm solution with and without CS shrinkage (170 equations vs. 80 equations).

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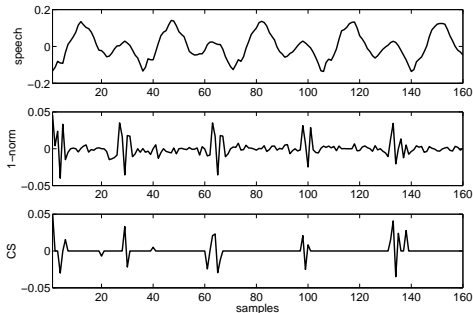
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## Compressed Sensing in Sparse LP - Example



CS recovery of the sparse residual. The imposed sparsity level is  $T = 20$ , corresponding to the size  $M = 80$  for the sensing matrix.

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# Sparse Linear Prediction

## Analysis

- ▶ Main advantage is to overcome some of 2-norm LP known issues
  - ▶ Lower Spectral Distortion for the spectral envelope estimation.
  - ▶ Invariant to small shift of the analysis window.
  - ▶ Pitch Independence.

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# Sparse Linear Prediction

## Coding

- ▶ Synergistic multi-stage coding (sparse predictor  $\rightarrow$  sparse encoding).
- ▶ Possibility variable rate coding through high-order predictor modeling ( $\rightarrow$  model order selection and intrinsic V/UV classification).
- ▶ More “fair” distribution between bit allocations on  $\mathbf{a}$  and  $\mathbf{r}$ .
- ▶ Less parameters necessary.

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# Sparse Linear Prediction

## Drawbacks

- ▶ Stability not guaranteed. Defined new methods to tackle this problem:
  - ▶ Reducing the numerical range of the shift operator.
  - ▶ Constrained 1-norm based on the alternative Cauchy bound.
- ▶ Computational Complexity:
  - ▶ Compressed Sensing reduces the number of constraints.
  - ▶ Efficient convex optimization algorithms tailor made for LP.
  - ▶ Much of the total computational cost in a speech coder is saved by the “one-step” procedure.
- ▶ Non-Uniqueness (still optimal!).
- ▶ Lack of a Frequency-Domain interpretation.

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## References

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# Sparsity in LPAS Coders

## Rate-Distortion Perspective

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- ▶ Minimize distortion between the original signal  $\mathbf{x}$  and its synthesized version  $\hat{\mathbf{x}}$  subject to some constraints regarding the rate:

$$\begin{aligned} & \text{minimize} && D(\mathbf{x}, \hat{\mathbf{x}}), \\ & \text{subject to} && R(\hat{\mathbf{x}}) \leq R^*. \end{aligned}$$

where  $D(\mathbf{x}, \hat{\mathbf{x}})$  is the distortion measure,  $R(\hat{\mathbf{x}})$  is the rate used to describe  $\hat{\mathbf{x}}$ , and  $R^*$  is the maximum possible rate.

# Sparsity in LPAS Coders

## Distortion

- ▶ In LPAS coders The distortion  $D(\mathbf{x}, \hat{\mathbf{x}})$  is directly associated with the choice of the predictor  $\hat{\mathbf{a}}$  and the prediction residual  $\hat{\mathbf{r}}$ :

$$D(\mathbf{x}, \hat{\mathbf{x}}) = \|\mathbf{W}(\mathbf{x} - \Upsilon(\hat{\mathbf{a}})\hat{\mathbf{r}})\|_2,$$

where  $\mathbf{H} = \Upsilon(\mathbf{a})$  is the synthesis matrix used in the AbS equations (nonlinear transformation of  $\mathbf{a}$ ) and  $\Upsilon(\cdot)$  being the nonlinear operator that maps  $\mathbf{a}$  into  $\mathbf{H}$ .

- ▶  $\mathbf{W}$  is the matrix that performs the projection in the perceptual domain.

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## Rate and Sparsity

- ▶ Distortion is related to the selection of  $\hat{\mathbf{a}}$  and  $\hat{\mathbf{r}}$ , we can split the rate accordingly:

$$R(\hat{\mathbf{x}}) = R(\hat{\mathbf{a}}) + R(\hat{\mathbf{r}}).$$

- ▶ If we consider the cardinality of the two vectors as a coarse approximation of the rate:

$$R(\hat{\mathbf{x}}) \cong \alpha \|\hat{\mathbf{a}}\|_0 + \beta \|\hat{\mathbf{r}}\|_0,$$

- ▶ we can reformulate the problem as (using Lagrange Multipliers):

$$\hat{\mathbf{a}}, \hat{\mathbf{r}} = \arg \min_{\mathbf{a}, \mathbf{r}} \|\mathbf{W}(\mathbf{x} - \Upsilon(\mathbf{a})\mathbf{r})\|_2^2 + \gamma(\alpha \|\mathbf{a}\|_0 + \beta \|\mathbf{r}\|_0).$$

- ▶ The problem is nonconvex, and nonlinear! Use of convex relaxation and alternate minimization to solve it.

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# Alternate Minimization Procedure

## Estimating Sparse High-Order LP and Residual

- ▶ Initial  $\mathbf{a}$  estimate via Sparse LP, determine  $\mathbf{H}$ .
- ▶ Exploiting prior knowledge on the sparsity:

$$\hat{\mathbf{r}} = \arg \min_{\mathbf{r}} \|\mathbf{r}\|_1 \quad \text{s.t.} \quad \Phi \mathbf{x} = \Phi \mathbf{H} \mathbf{r}.$$

- ▶ Known  $\mathbf{r}$ , we estimate  $\mathbf{a}$ :

$$\hat{\mathbf{a}} = \arg \min_{\mathbf{a}} \|\mathbf{x} - \Upsilon(\mathbf{a})\mathbf{r}\|_2^2 + \chi \|\mathbf{a}\|_0,$$

- ▶ Calculate a minimum variance approximation of the impulse response:

$$\hat{\mathbf{H}} = \min_{\mathbf{H}} \|\mathbf{x} - \mathbf{H}\mathbf{r}\|_2^2 \quad \leftrightarrow \quad \hat{\mathbf{h}} = \min_{\mathbf{h}} \|\mathbf{x} - \mathbf{R}\mathbf{h}\|_2^2$$

- ▶ Ultimately, recalculate the predictor:

$$\hat{\mathbf{a}} = \arg \min_{\mathbf{a}} \|\mathbf{a}\|_1 \quad \text{s.t.} \quad \Psi \mathbf{t}'' + \Psi \mathbf{T}'' \mathbf{a} = \mathbf{0}.$$

where  $\mathbf{A}\mathbf{T} = \mathbf{I}$ ,  $\mathbf{t} = \hat{\mathbf{h}} = \mathbf{R}^{-1}\mathbf{x}$  is the minimum norm solution  $\mathbf{x} - \mathbf{T}\mathbf{r} = \mathbf{0}$ .

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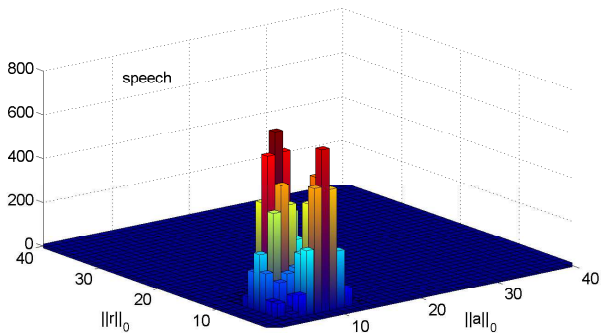
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# Alternate Minimization Procedure

## Observations

- ▶ Needs a priori knowledge of the sparsity of  $\mathbf{a}$  and  $\mathbf{r}$  to determine the size of the random matrices for the CS formulations.
- ▶ Creates extremely sparse solutions.



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# Application of sparsity in LPAS

## Frame Dependent/Independent Coding

- ▶ We apply the rate/distortion sparse approach to the problem of speech coding robust to packet loss.
- ▶ An approach to cope high packet loss in VoIP is to create speech coders that are totally frame independent.
- ▶ In the case of telephony with dedicated circuits, high quality is achieved by the exploitation of inter-frame dependencies.

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# Application of sparsity in the LPAS

## Frame Dependent/Independent Coding

- ▶ Frame independent are created cope with packet loss
- ▶ Frame dependent coders achieve high quality by the exploitation of inter-frame dependencies.
- ▶ Splitting the information present in each speech packet into two components:
  - ▶ one to independently decode the given speech frame,
  - ▶ one to enhance it by exploiting inter-frame dependencies.
- ▶ We formulate the problem as:

$$\begin{aligned} \min. \quad & D(\mathbf{x}, \hat{\mathbf{x}}^{FI} + \hat{\mathbf{x}}^{EN}) \\ \text{s.t.} \quad & R(\hat{\mathbf{x}}^{FI}) + R(\hat{\mathbf{x}}^{EN}) \leq R^*. \end{aligned}$$

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# Sparsity in LPAS Coders

## Minimization Problem

- ▶ This problem in a LPAS framework can then be formulated as:

$$\arg \min_{\mathbf{a}, \mathbf{r}} \|\mathbf{x} - \Upsilon(\mathbf{a}^{FI} + \mathbf{a}^{EN})(\mathbf{r}^{FI} + \mathbf{r}^{EN})\|_2 + \chi \|\mathbf{a}^{FI} + \mathbf{a}^{EN}\|_0 + \delta \|\mathbf{r}^{FI} + \mathbf{r}^{EN}\|_0.$$

- ▶ The frame independent parameters are calculated without state memory:

$$\hat{\mathbf{a}}^{FI}, \hat{\mathbf{r}}^{FI} = \arg \min_{\mathbf{a}, \mathbf{r}} \|\mathbf{x} - \Upsilon(\mathbf{a}^{FI})\mathbf{r}^{FI}\|_2 + \chi \|\mathbf{a}^{FI}\|_0 + \delta \|\mathbf{r}^{FI}\|_0.$$

- ▶ The frame dependent parameters are calculated with state memory ( $\mathbf{r}^{FD} = [\hat{\mathbf{r}}_-^T, \mathbf{r}^T]^T$ ):

$$\hat{\mathbf{a}}^{FD}, \hat{\mathbf{r}}^{FD} = \arg \min_{\mathbf{a}, \mathbf{r}} \|\mathbf{x} - \Upsilon(\mathbf{a}^{FD})(\mathbf{r}^{FD})\|_2 + \chi \|\mathbf{a}^{FD}\|_0 + \delta \|\mathbf{r}^{FD}\|_0.$$

# Frame Dependent/Independent Coding

## General Behavior

- ▶ The reconstructed speech for the frame independent case:

$$\hat{\mathbf{x}}^{FI} = \Upsilon(\mathbf{a}^{FI})\hat{\mathbf{r}}^{FI},$$

- ▶ For the frame dependent case:

$$\hat{\mathbf{x}}^{FD} = \Upsilon(\mathbf{a}^{FD}) \left[ (\hat{\mathbf{r}}_{-1}^{FD})^T, (\hat{\mathbf{r}}^{FD})^T \right]^T.$$

- ▶ We transmit the frame independent parameters  $(\hat{\mathbf{r}}^{FI}, \hat{A}^{FI}(z))$  and a side stream with the differences between the two predictors  $\hat{A}^{EN}(z)$  and the differences between the two residuals  $\hat{\mathbf{r}}^{EN}(z)$ .
- ▶ Multipulse encoding.

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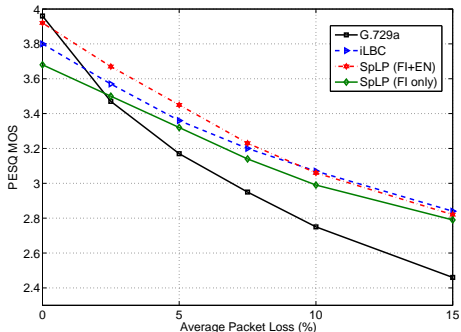
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# Frame Dependent/Independent Coding Results



Performances of the compared methods: G.729a (8 kbps), iLBC (13.33 kbps), and our method (SpLP) with (FI+EN) and without (FI) the frame dependent enhancement layer (respectively 10.9 and 7.65 kbps).

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# Sparse Linear Prediction

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# Conclusions

## Sparsity in the LP optimization framework

- ▶ Analysis: a more efficient decoupling between the pitch harmonics and the spectral envelope.
- ▶ Coding: a more straightforward approach to encode a speech segment.
- ▶ Sparse LP applied successfully also in audio processing, transcending some of the limitation of traditional LP.

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# Conclusions

## Sparsity in the LPAS framework

- ▶ New method for the estimation of the parameters in speech coding, creating a new meaning for the LP parameters.
- ▶ Providing tradeoffs between the complexity, and thus the bit-rate, of the two descriptions.
- ▶ Highly flexible: possibility of estimating predictors and residuals that create a independently decodable frames of audio and speech.

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