

# Perceptual Evaluation of Numerical Auditory Scene Synthesis Using Loudspeaker Arrays

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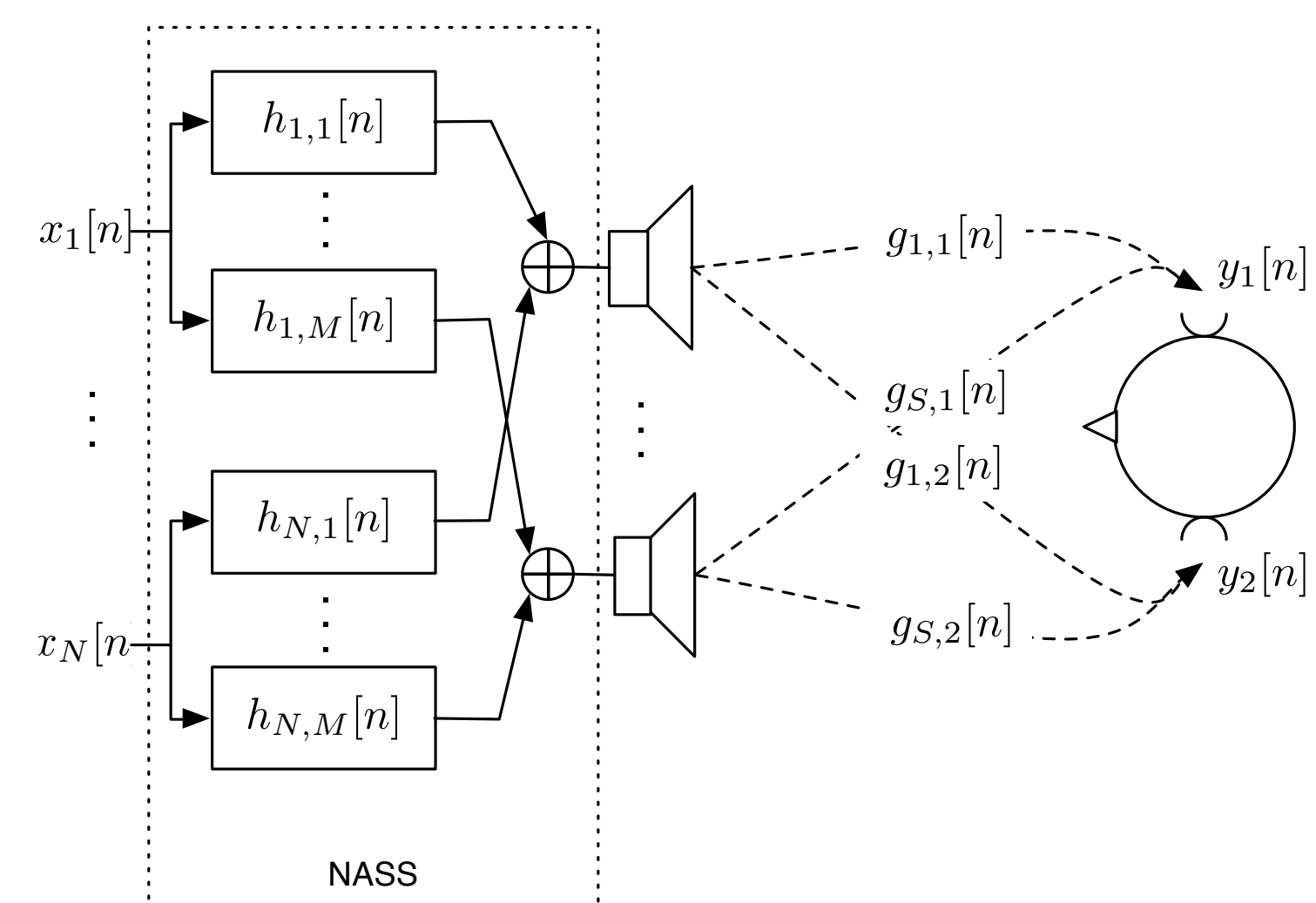
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## Introduction

- There are many methods used to achieve a spatial sound field, such as Loudspeaker Binaural Rendering (LBR) (1), Wave-field Synthesis (WFS) (2), Vector-base Amplitude Panning (VBAP) (3), Higher Order Ambisonics (HOA) (4), and Equivalent Source Method (ESM) (5).
- There is limited literature on the perceptual evaluation of spatial sound synthesis methods (6).
- We introduced numerical auditory scene synthesis (NASS) in (7); a flexible numerical method that allows for broadband filter design and the incorporation of perceptual error.
- We present evaluations of timbral and spatial quality using variations of the NASS method for the task of simulating a single source outside the aperture of an 8 speaker array.

## 1 Methodology



NASS system for simulating binaural sources over loudspeakers with N input sources and S loudspeakers and M=2 target points.

- $N_g, N_h, N_t$ : lengths of the acoustic path, filter, and desired response, respectively.
- $D, S, M$ : modeling delay, number of speakers, and number of target points, respectively.
- $\mathbf{Z}$  and  $\mathbf{W}$  represent spatio-temporal transforms.
- $p, q, \delta$  represent the cost function norm, constraint norm, and constraint threshold, respectively.

$$\mathbf{t}_L = [0, \dots, 0, t_L[0], \dots, t_L[N_t - 1], 0, \dots, 0]$$

$$\mathbf{t}_R = [0, \dots, 0, t_R[0], \dots, t_R[N_t - 1], 0, \dots, 0]$$

$$\mathbf{t} = [t_L, t_R]^T$$

Underdetermined Case ( $SN_h \geq MN_t, \text{Rank}(\mathbf{G}) = MN_t$ )

$$\hat{\mathbf{h}} = \arg \min_{\mathbf{h}} \|\mathbf{h}\|_q \quad \text{s. t.} \quad \mathbf{G}\mathbf{h} = \mathbf{t}$$

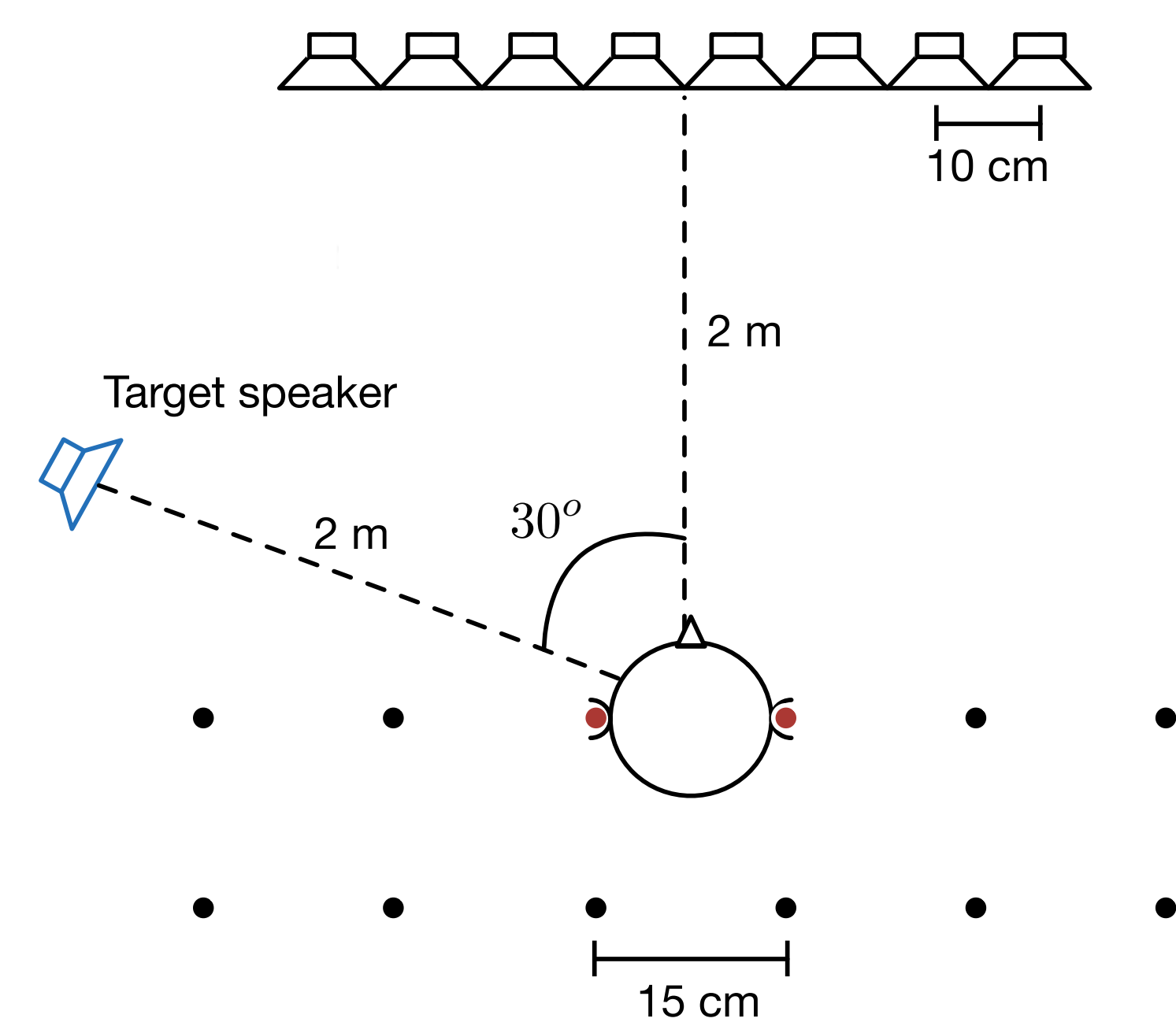
Acoustic IR      Target Response

Overdetermined Case ( $SN_h < MN_t, \text{Rank}(\mathbf{G}) = SN_h$ )

$$\hat{\mathbf{h}} = \arg \min_{\mathbf{h}} \|\mathbf{W}(\mathbf{G}\mathbf{h} - \mathbf{t})\|_p \quad \text{s. t.} \quad \|\mathbf{Z}\mathbf{h}\|_q \leq \delta$$

Spatio-temporal Projection      Acoustic IR      Target Response      Projection      Constraint

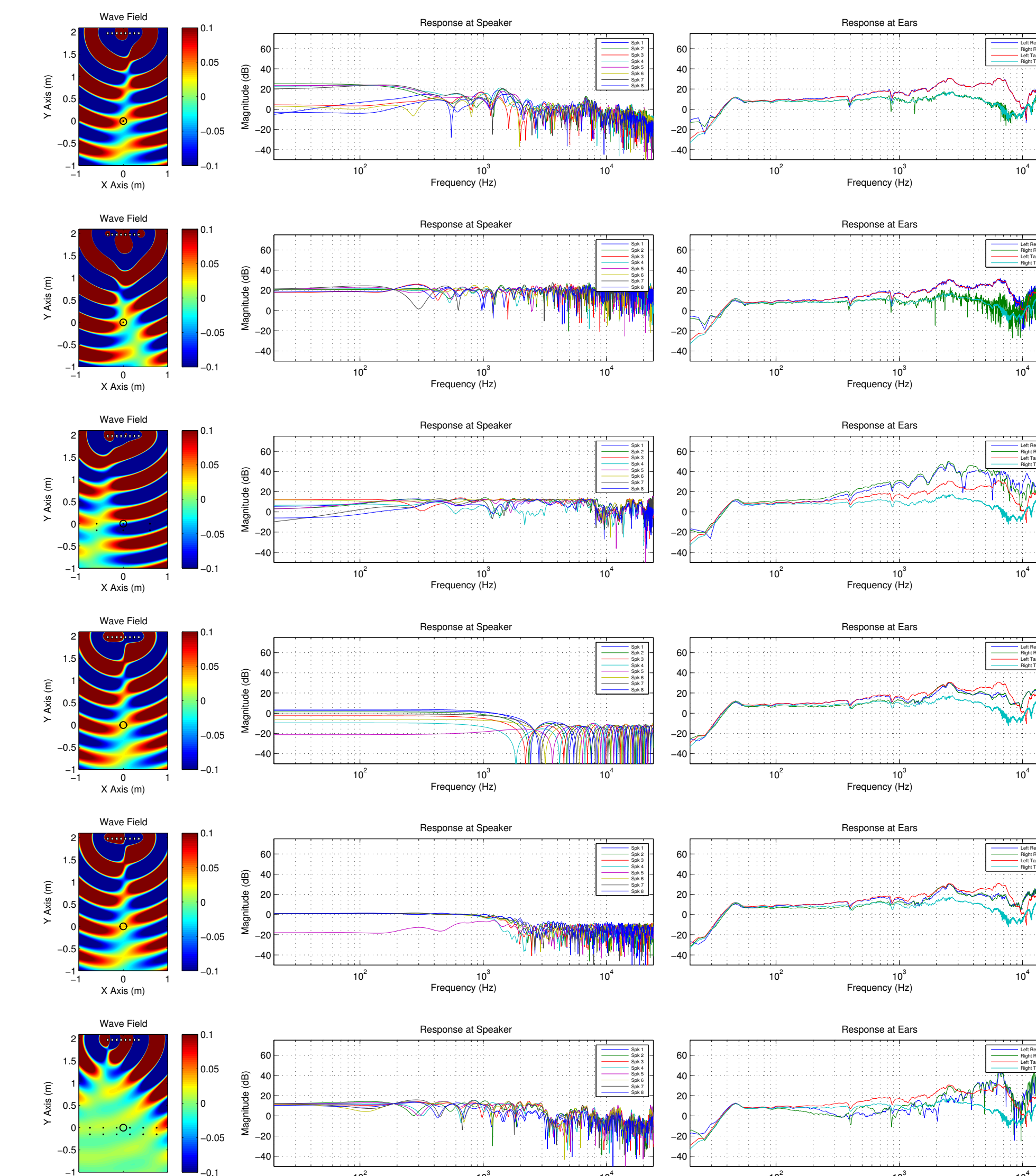
## 2 Evaluation



Measurement and simulation setup.

- Filters designed for 8 channel uniform linear array.
- $\mathbf{G}$  and  $\mathbf{t}$  are represented by measured HRTF or a spherical wave propagation model.
- The following HRTFs and spherical wave based configurations were evaluated:
  - HRTF,  $q = 2, M = 2$  (HRTF2\_L2)
  - HRTF,  $q = \infty, M = 2$  (HRTF2\_Li)
  - HRTF,  $q = \infty, M = 12, p = 2, \delta = 12$  dB (HRTF12\_Li)
  - Spherical Wave,  $q = 2, M = 2$  (WAVE2\_L2)
  - Spherical Wave,  $q = \infty, M = 2$  (WAVE2\_Li)
  - Spherical Wave,  $q = \infty, M = 12, p = 2, \delta = 12$  dB (WAVE12\_Li)
- In all cases,  $N_g = N_h = 256, D = 100$ , and  $N_t = 411$ .

## 2.1 Objective Evaluation

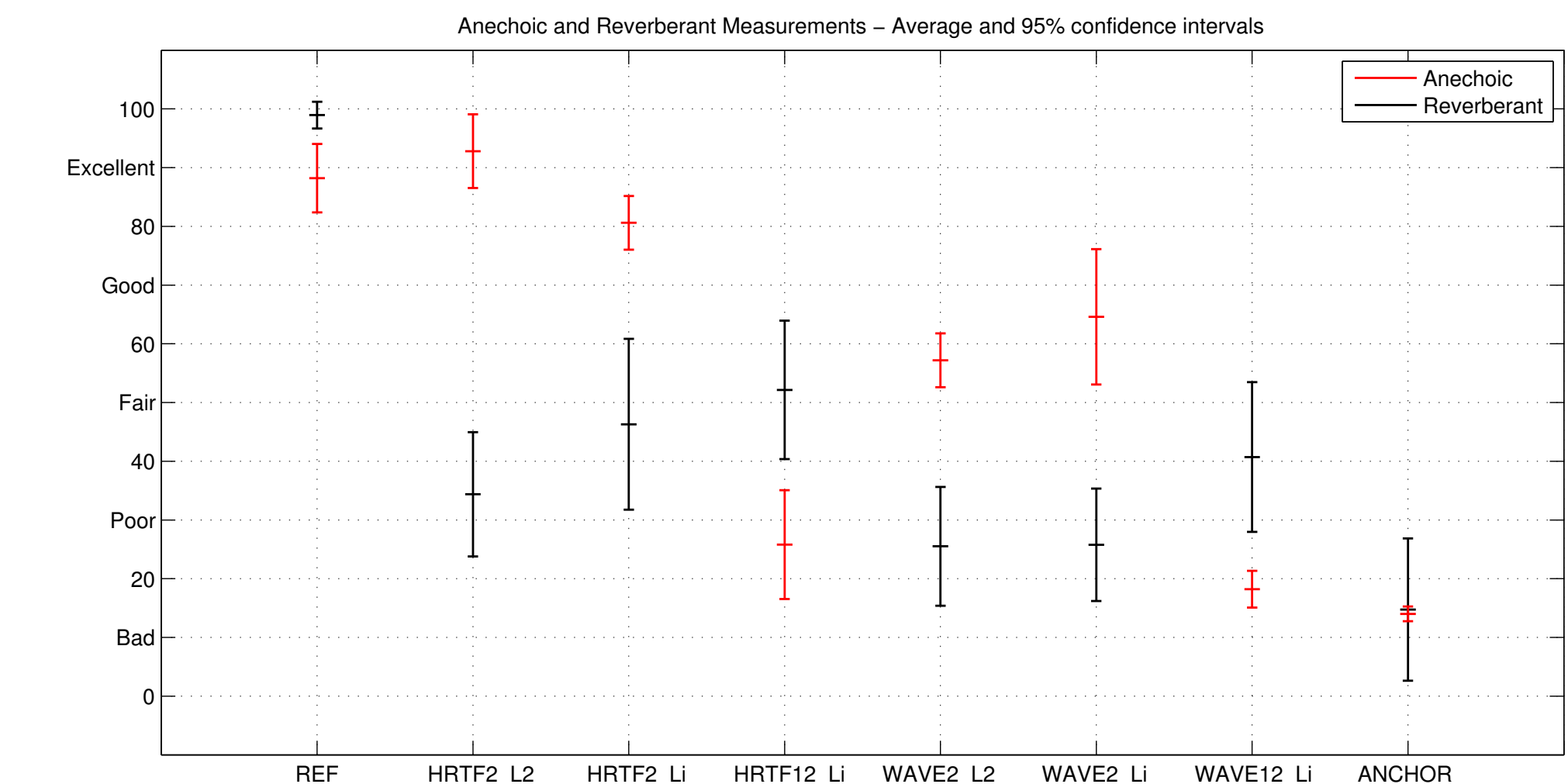


From top to bottom: HRTF2\_L2, HRTF2\_Li, HRTF12\_Li, WAVE2\_L2, WAVE2\_Li, and WAVE12\_Li. The graphs represent, from left to right, the wave field at 500 Hz, the filter frequency response, and the response at the ears.

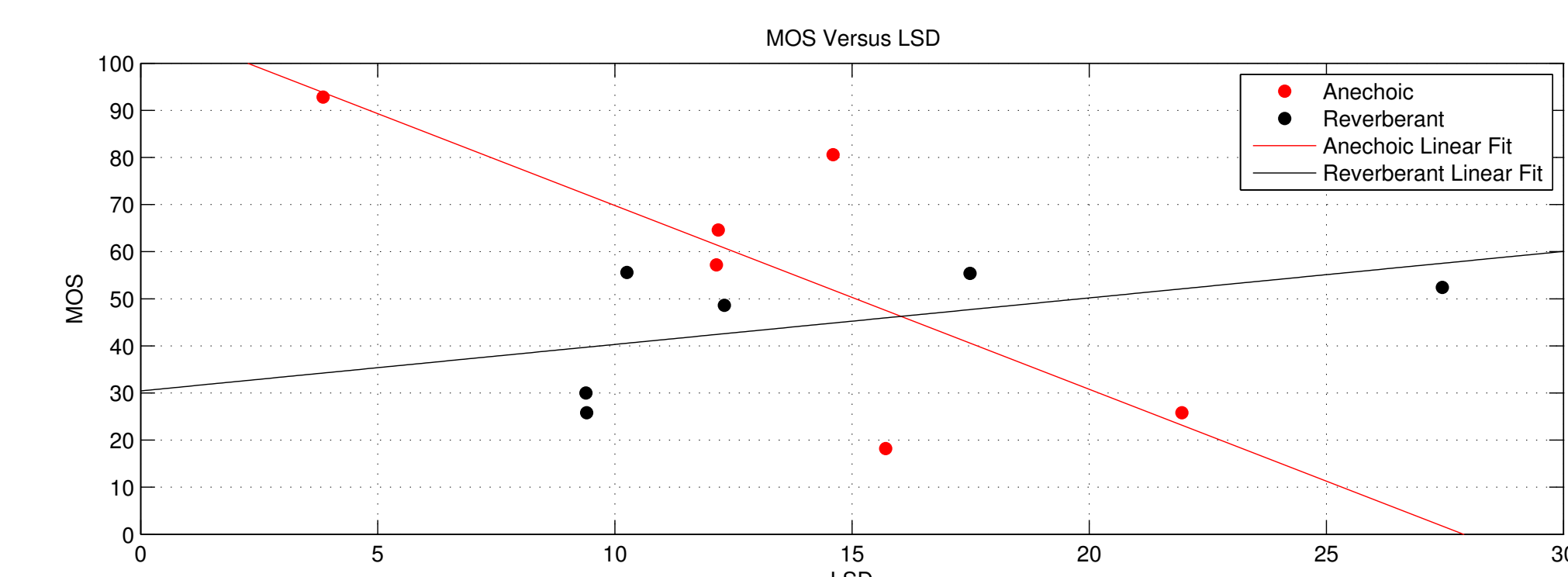
- Underdetermined cases are not spatially robust; the filters are optimized for the center position.
- The HRTF underdetermined cases closely match the expected ear responses at the central position.
- Spherical wave methods, though generating the expected acoustical waveform, don't achieve the desired responses.
- In overdetermined cases, filters are optimized for a larger spatial region resulting in increased error.

## 2.2 Subjective Evaluation

- 13 listeners; 9 experts and 4 naïve.
- Five audio excerpts were evaluated: castanets, pink noise, music, male voice, and female voice.
- Two tasks:
  - Array and reference speaker in anechoic room.
  - Array and reference speaker in reverberant room.
- Anchor is decorrelated and low-pass filtered.
- MUSHRA evaluations conducted on headphones.



MUSHRA results for evaluated spatial reproduction methods.



Log spectral distortion vs. MOS. Correlation Coefficients: -0.78 (anechoic) and 0.53 (reverberant).

- HRTF-based methods tended to perform better.
- Underdetermined cases performed better in anechoic cases while overdetermined cases performed better in reverberant cases.
- MOS and LSD show a strong relationship during anechoic simulation, but weak for reverberant.

## 3 Conclusion

- HRTF outperforms spherical wave representation.
- Mismatch between anechoic algorithm design and deployment in a real room.
- Perceptually relevant metrics should be used.
- Future work compares the proposed and conventional crosstalk-based spatial rendering and optimizes the number of speakers and filter length.

## References

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- (2) A.J. Berkhout, et al., "Acoustic control by wave field synthesis," *J. ASA*, vol. 93, 1993.
- (3) V. Pulkki, "Virtual sound source positioning using vector base amplitude panning," *J. AES*, vol. 45, no. 6, 1997.
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- (5) G. H. Koopmann, et al., "A method for computing acoustic fields based on the principle of wave superposition," *J. ASA*, vol. 86, no. 6, 1989.
- (6) F. Rumsey, et al., "QESTRAL (part 1): quality evaluation of spatial transmission and reproduction using an artificial listener," *Proc. 125th AES Conv.*, 2008.
- (7) J. Atkins, I. Nawfal, and D. Giacobello, "A unified approach to numerical auditory scene synthesis using loudspeaker arrays," *Proc. EUSIPCO*, 2014.